BI-DIRECTIONAL DC MOTOR DRIVER

The KA8306 is a monolithic integrated circuit designed for driving bi-directional DC motor with a dual bridge driver, and it is suitable for the cassette and loading motor driver of VCR systems.

FEATURES

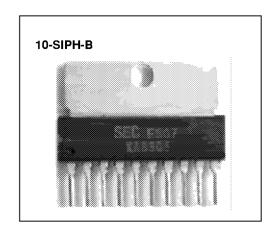
- 4 modes available (CW/CCW/STOP/BRAKE)
- Output current up to 1.0A (AVE.) and 1.5A (PEAK)
- Wide range of operating voltage

$$-V_{CC} = 4.5 \sim 18V$$

$$-V_S = 0 \sim 18V$$

$$-V_{RFF} = 0 \sim 18V$$

 Build in thermal shutdown, over current protector and punch through current restriction circit.



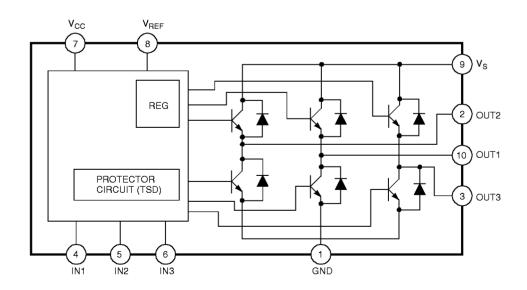
ORDERING INFORMATION

Device	Package	Operating Temperature
K A 8306	10-SIPH-B	−25°C ~ +75°C

TARGET APPLICATION

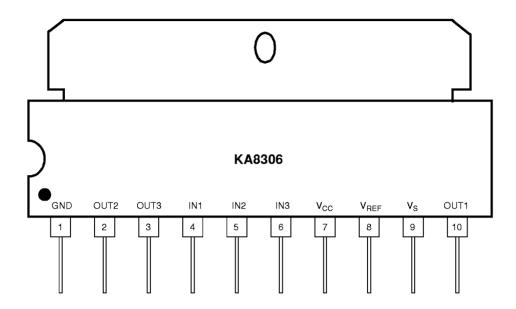
- VCR
- Low current DC motor such audio equipment

BLOCK DIAGRAM





PIN CONFIGURATIONS



PIN DESCRIPTION

Pin No.	Symbol	I/O	Description	Pin No.	Symbol	I/O	Description	
1	GND	_	Ground	6	IN3	I	Input 3	
2	OUT2	0	Output 2	7	V _{CC}	_	Supply voltage (Signal)	
3	OUT3	0	Output 3	8	V _{REF}	I	Motor speed control	
4	IN1	I	Input 1	9	Vs	1	Supply voltage (Power)	
5	IN2	I	Input 2	10	OUT1	0	Output 1	



INTERNAL CIRCUIT

Description	Pin No.	Internal circuit
Input	4, 5, 6	Input terminals of pins 4, 5 and 6 are all high active type and have a hysteresis of 0.7V type 5µA type of source mode input current is required.
Output	2, 3, 10	Output voltage is controlled by V _{REF} voltage relationship between V _{OUT} and V _{REF} is V _{OUT} =V _{BE} (=0.7)+V _{REF} V _{REF} ternianl required to connect to V _S terminal for stable operation in case of no requirement of V _{OUT} control.

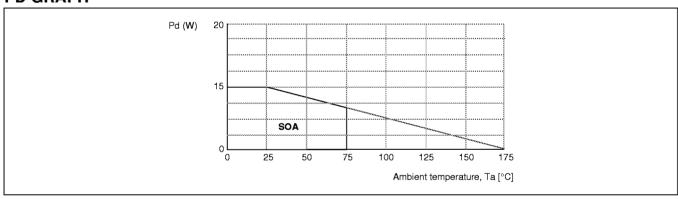
ABSOLUTE MAXIMUM RATING (Ta=25°C)

Characteristics	Symbol	Value	Unit
Supply voltage	V _{CCmax}	25	V
Motor drive voltage	V _{Smax}	25	V
Reference voltage	V _{REFmax}	25	V
Maximum output current	l _{Omax(} PEAK) l _{Omax(} AVE)	1.5 ^{note1} 1.0	A A
Power dissipation	P _d	15 ^{note2}	W
Operating temperature	T _{OPR}	−25 ~ +75	°C
Storage temperature	T _{STG}	−55 ~ +150	°C

NOTES:

- 1. Duty 1/100, pulse width 500μs
- 2. 1) When mounted on glass epoxy PCB $(76.2 \times 114 \times 1.57 \text{mm})$
 - 2) Power dissipation reduces 103.4mW / °C for using above Ta=25°C
 - 3) Do not exceed Pd and SOA.

PD GRAPH



RECOMMENED OPERATING CONDITIONS (Ta=25°C)

Characteristics	Symbol	Value	Unit
Operating supply voltage	V _{CC}	4.5 ~ 18	V



ELECTRICAL CHARACTERISTICS

(Unless otherwise specified, Ta=25°C, V_{CC} =8V, R_L =8 Ω , f=1kHz)

Characteristics		Symbol	Test	Test Test conditions		Spec.		
		Symbol circuit Test conditions		rest conditions	Min.	Тур.	max.	Unit
Supply current		l _{CC1}	1	Output off CW/CCW mode	-	17	30	mA
		I _{CC2}	1	Output off, stop mode	_	13	25	mA
Input operating	Н	V _{IN-H}	2	T _J =25°C		-	5.5	٧
voltage	L	V _{IN-L}	2	T _J =25°C	0	-	0.8	٧
Input current	l	I _{IN}	2	V _{IN} =3.5V, Sink mode	_	5	20	μΑ
Input hysteresis voltage		V _{HYS}	2	_	_	0.7	-	٧
Saturation	Upper	V _{SAT-1U}	3	V _{REF} =V _S , I _O =0.2A	_	1.2	1.5	٧
voltage	Lower	V _{SAT-1L}	3	V _{REF} =V _S , I _O =0.2A	_	1.1	1.4	٧
	Upper	V _{SAT-2U}	3	V _{REF} =V _S , I _O =1.0A	_	2.7	3.1	٧
	Lower	V _{SAT-2L}	3	V _{REF} =V _S , I _O =1.0A	_	2.5	3.0	٧
Output voltage		V _{O-1}	3	V _{REF} =10V, I _O =0.5A Output measure	10.3	10.7	11.5	٧
		V _{O-2}	3	V _{REF} =10V, I _O =0.5A Output measure	10.1	10.5	11.3	٧
Leakage current Upper		I _{L-U}	_	V _S =25V	_	0	50	μΑ
	Lower	I _{L-L}	_	V _S =25V	_	0	50	μΑ
Diode forward	Upper	V _{F-U}	4	I _F =1.0A	_	2.2	_	٧
voltge	Lower	V _{F-L}	4	I _F =1.0A	_	1.4	_	٧
Reference current		I _{REF}	2	V _{REF} =10V, Source mode	_	20	30	μΑ



APPLICATION INFORMATIONS

LOGIC INPUT & OUTPUT TABLE

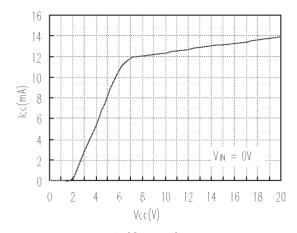
Input ^{note1}		Output			Motor		
IN ₁	IN ₂	IN ₃	OUT ₁	OUT ₂	OUT ₃	M ₁	M ₂
0	0	1/0	L	L	L	Brake	Brake
1	0	0	Н	L	note2	Pin10→2	Stop
1	0	1	L	Н	note2	Pin10→10	Stop
0	1	0	Н	note2	L	Stop	Pin10→3
0	1	1	L	note2	Н	Stop	Pin3→10
1	1	1/0	L	L	L	Brake	Brake

NOTES:

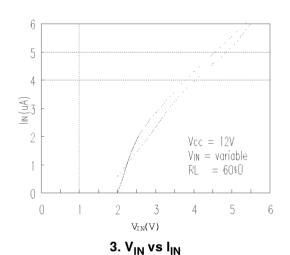
- 1. Inputs are all high active type
- 2. High impedance



CHARACTERISTIC GRAPHS



1. V_{CC} vs I_{CC}



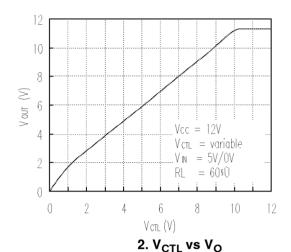
≥ 2.5 ≥ 2.0 ≥ 1.5 1.0 0.5 0.0 ≥ 2.5 Vcc = 12V VcπL = open V N = 5V/OV RL = variable

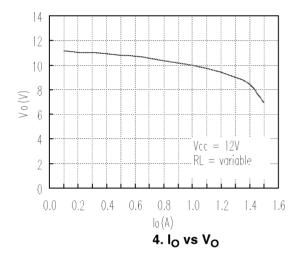
0.6

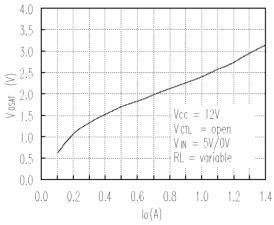
 $\log \langle \mathbb{A} \rangle$ 5. I_O vs V_{SAT} (Upper)

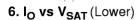
8.0

1.0











0.0

0.2

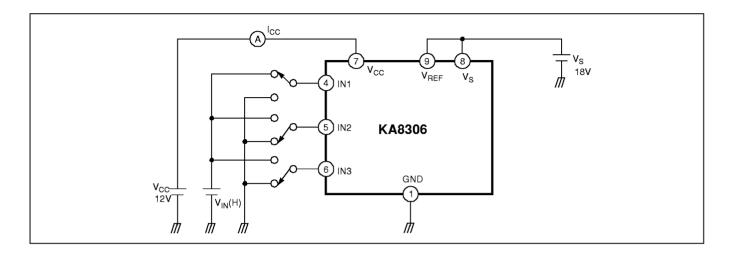
0.4

4.0

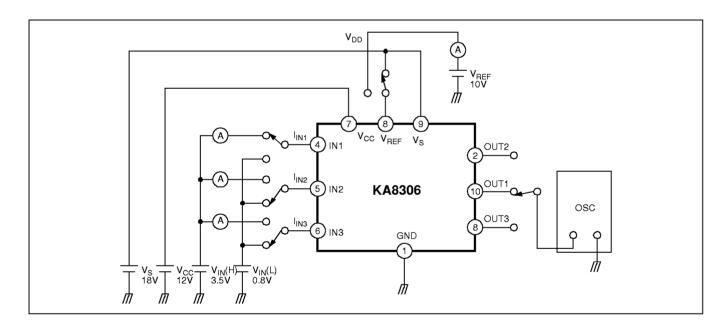
3.5

3.0

TEST CIRCUIT 1

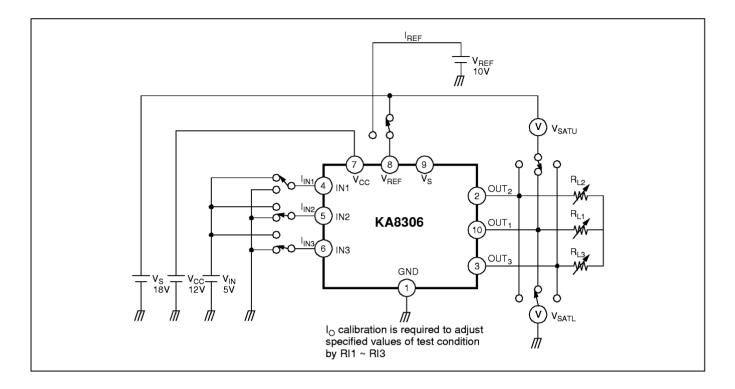


TEST CIRCUIT 2

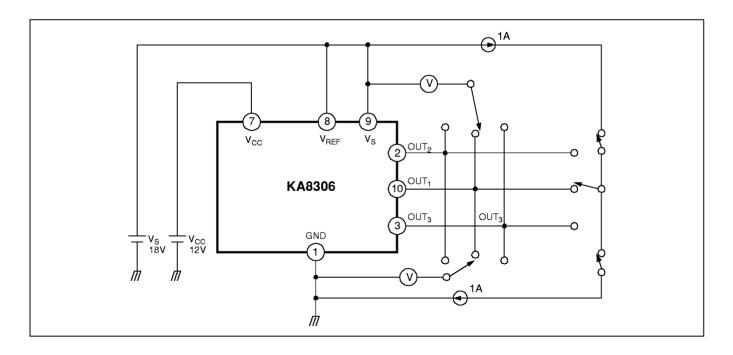




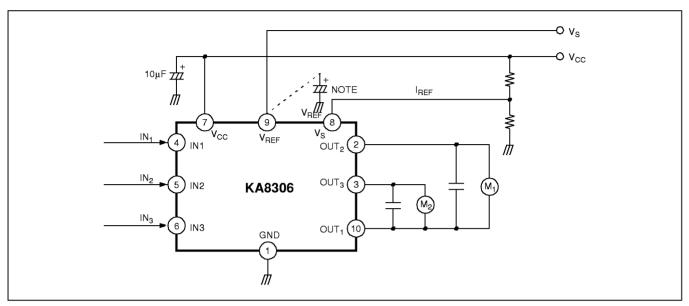
TEST CIRCUIT 3



TEST CIRCUIT 4



APPLICATION CIRCUIT



NOTE: Connect if required

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