TOSHIBA Bipolar Digital Integrated Circuit Silicon Monolithic

# TD62308AP,TD62308AF

#### 4ch Low Input Active High-Current Darlington Sink Driver

The TD62308AP/AF is a non-inverting transistor array which is comprised of four NPN darlington output stages and PNP input stages.

This device is low-level input active driver and is suitable for operation with 5-V TTL, 5-V CMOS and 5-V Microprocessor which have sink current output drivers.

Application include relay, hammer, lamp and stepping motor drivers.

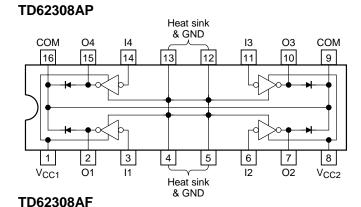
#### **Features**

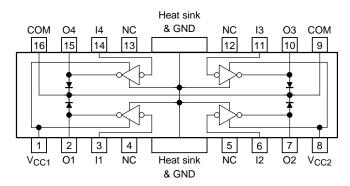
- Output current (single output): 1.5 A (max)
- High sustaining voltage output: 50 V (min)
- · Output clamp diodes
- Input compatible with TTL and 5 V CMOS
- · Low level active inputs
- · Standard supply voltage
- Two VCC terminals VCC1, VCC2 (separated)
- GND and SUB terminal = Heat sink
- Package type-AP: DIP-16 pin
- Package type-AF: HSOP-16 pin

# DIP16-P-300-2.54A TD62308AF HSOP16-P-300-1.00

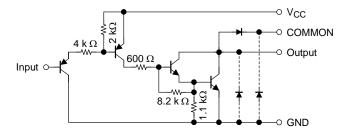
Weight DIP16-P-300-2.54A: 1.11 g (typ.) HSOP16-P-300-1.00: 0.50 g (typ.)

#### Pin Assignment (top view)





#### Schematics (each driver)



Note: The input and output parasitic diodes cannot be used as clamp diodes.

#### **Precautions for Using**

- (1) This IC does not include built-in protection circuits for excess current or overvoltage. If this IC is subjected to excess current or overvoltage, it may be destroyed. Hence, the utmost care must be taken when systems which incorporate this IC are designed. Utmost care is necessary in the design of the output line, VCC, COMMON and GND line since IC may be destroyed due to short-circuit between outputs, air contamination fault, or fault by improper grounding.
- (2) If a TD62308AP/AF is being used to drive an inductive load (such as a motor, solenoid or relay), Toshiba recommends that the diodes (pins 9 and 16) be connected to the secondary power supply pin so as to absorb the counter electromotive force generated by the load. Please adhere to the device's absolute maximum ratings. Toshiba recommends that zener diodes be connected between the diodes (pins 9 and 16) and the secondary power supply pin (as the anode) so as to enable rapid absorption of the counter electromotive force. Again, please adhere to the device's absolute maximum ratings.

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#### **Absolute Maximum Ratings (Ta = 25°C)**

| Characteristics             |    | Symbol                | Rating               | Unit |  |
|-----------------------------|----|-----------------------|----------------------|------|--|
| Supply voltage              |    | V <sub>CC</sub>       | -0.5 to 10           | V    |  |
| Output sustaining voltage   |    | V <sub>CE</sub> (SUS) | -0.5 to 50           | V    |  |
| Output current              |    | l <sub>OUT</sub>      | 1.5                  | A/ch |  |
| Input current               |    | I <sub>IN</sub>       | -10                  | mA   |  |
| Input voltage               |    | V <sub>IN</sub>       | -0.5 to 30           | ٧    |  |
| Clamp diode reverse voltage |    | V <sub>R</sub>        | 50                   | V    |  |
| Clamp diode forward current |    | I <sub>F</sub>        | 1.5                  | Α    |  |
| Power dissipation           | AP | D <sub>-</sub>        | 1.47/2.7<br>(Note 1) | W    |  |
|                             | AF | P <sub>D</sub>        | 0.9/1.4<br>(Note 2)  | VV   |  |
| Operating temperature       |    | T <sub>opr</sub>      | -40 to 85            | °C   |  |
| Storage temperature         |    | T <sub>stg</sub>      | -55 to 150           | °C   |  |

Note 1: On glass epoxy PCB ( $50 \times 50 \times 1.6$  mm Cu 50%)

Note 2: On glass epoxy PCB ( $60 \times 30 \times 1.6$  mm Cu 30%)



# Recommended Operating Conditions ( $Ta = -40 \text{ to } 85^{\circ}\text{C}$ )

| Characteristics             |            | Symbol                | Test Condition   |            | Min                     | Тур. | Max                     | Unit  |  |
|-----------------------------|------------|-----------------------|--|------------|-------------------------|------|-------------------------|-------|--|
| Supply voltage              |            | V <sub>CC</sub>       | _  |            | 4.5                     | _    | 5.5                     | V     |  |
| Output sustaining voltage   |            | V <sub>CE</sub> (SUS) | _  |            | 0                       | _    | 50                      | V     |  |
|                             |            |                       | DC1 circuit, Ta = 25°C                                       |            | 0                       | _    | 1250                    |       |  |
| Output current              | AP         | l <sub>OUT</sub>      | $T_{pw}$ = 25 ms<br>4 circuits<br>Ta = 85°C<br>$T_j$ = 120°C | Duty = 10% | 0                       | _    | 1250                    | mA/ch |  |
|                             |            |                       |  | Duty = 50% | 0                       | _    | 700                     |       |  |
|                             | AF         |                       |  | Duty = 10% | 0                       | _    | 1250                    |       |  |
|                             |            |                       |  | Duty = 50% | 0                       | _    | 390                     |       |  |
|                             |            | V <sub>IN</sub>       | _  |            | 0                       | _    | 25                      | V     |  |
| Input voltage               | Output ON  | VIN (ON)              | _  |            | 0                       | _    | V <sub>CC</sub><br>-3.6 | V     |  |
|                             | Output OFF | V <sub>IN (OFF)</sub> | _  |            | V <sub>CC</sub><br>-1.0 | _    | V <sub>CC</sub>         |       |  |
| Clamp diode reverse voltage |            | V <sub>R</sub>        | _  |            | _                       | _    | 50                      | V     |  |
| Clamp diode forward current |            | lF                    | _  |            | _                       | _    | 1.25                    | Α     |  |
| Power dissipation           | AP         | P <sub>D</sub>        | Ta = 85°C  | (Note 1)   | _                       | _    | 1.4                     | W     |  |
|                             | AF         |                       | Ta = 85°C  | (Note 2)   | _                       | _    | 0.7                     | VV    |  |

Note 1: On glass epoxy PCB ( $50 \times 50 \times 1.6$  mm Cu 50%)

Note 2: On glass epoxy PCB ( $60 \times 30 \times 1.6$  mm Cu 30%)

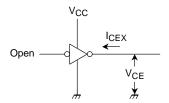
# **Electrical Characteristics (Ta = 25°C)**

| Characteristics             |            | Symbol                | Test<br>Circuit | Test Condition  | Min                     | Тур.  | Max                     | Unit  |  |
|-----------------------------|------------|-----------------------|-----------------|---|-------------------------|-------|-------------------------|-------|--|
| Output leakage current      |            | I <sub>CEX</sub>      | 1               | V <sub>CE</sub> = 50 V, Ta = 25°C   | _                       | _     | 50                      | μА    |  |
|                             |            |                       |                 | V <sub>CE</sub> = 50 V, Ta = 85°C   | _                       | _     | 100                     |       |  |
| Output saturation voltage   |            | V <sub>CE</sub> (sat) | 3               | I <sub>OUT</sub> = 1.25 A   | _                       | _     | 1.8                     | V     |  |
|                             |            |                       |                 | I <sub>OUT</sub> = 0.75 A   | _                       | _     | 1.3                     |       |  |
| Input voltage               | High level | $V_{IH}$              | _               | _   | V <sub>CC</sub><br>-1.6 | _     | 25                      | · V   |  |
|                             | Low level  | V <sub>IL</sub>       | _               | _   | _                       | _     | V <sub>CC</sub><br>-3.6 |       |  |
| Input current               | High level | I <sub>IH</sub>       | _               |   |                         | _     | 10                      | μА    |  |
|                             | Low level  | I <sub>IL</sub>       | _               | _   | _                       | -0.05 | -0.36                   | mA    |  |
| Clamp diode reverse current |            | $I_{R}$               | 4               | V <sub>R</sub> = 50 V, Ta = 25°C  | _                       | _     | 50                      | μА    |  |
| Clamp diode forward voltage |            | V <sub>F</sub>        | 5               | I <sub>F</sub> = 1.25 A   | _                       | 1.5   | 2.0                     | V     |  |
| Supply current              | Output ON  | I <sub>CC</sub> (ON)  | 2               | $V_{CC} = 5.5 \text{ V}, V_{IN} = 0 \text{ V}$  | _                       | 8.5   | 12.5                    | mA/ch |  |
|                             | Output OFF | I <sub>CC (OFF)</sub> |                 | $V_{CC} = 5.5 \text{ V}, V_{IN} = V_{CC}$   | _                       | _     | 1.0                     | μΑ    |  |
| Turn-ON delay               |            | t <sub>ON</sub>       | 6               | $\label{eq:classical_continuity} \begin{split} C_L &= 15 \text{ pF}, \text{ V}_{OUT} = 50 \text{ V}, \\ R_L &= 40 \Omega \end{split}$ | _                       | 0.2   | _                       | μS    |  |
| Turn-OFF delay              |            | t <sub>OFF</sub>      | 6               | $\begin{aligned} &C_L = 15 \text{ pF, V}_{OUT} = 35 \text{ V,} \\ &R_L = 40 \ \Omega \end{aligned}$                                   | _                       | 5.0   | _                       | μS    |  |

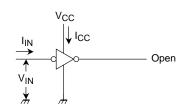
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## **Test Circuit**

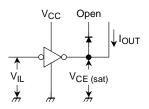
#### 1. ICEX



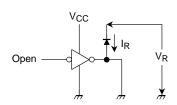
#### 2. Icc



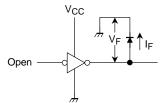
## 3. VCE (sat)



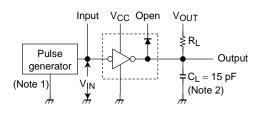
# 4. I<sub>R</sub>

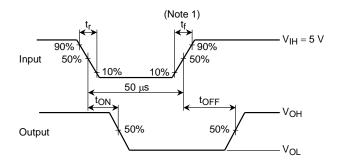


#### 5. V<sub>F</sub>



#### 6. ton, toff

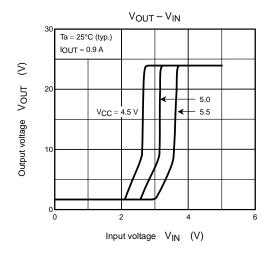


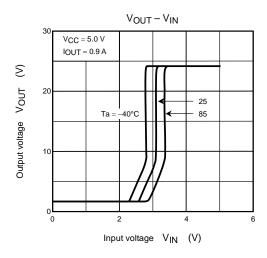


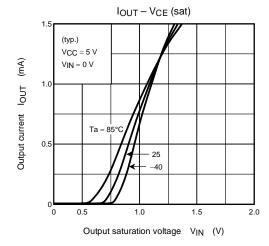
Note 1: Pulse Width 50  $\mu$ s, Duty Cycle 10%

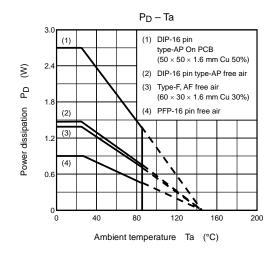
Output Impedance 50  $\Omega$ ,  $t_r \le 5$  ns,  $t_f \le 10$  ns

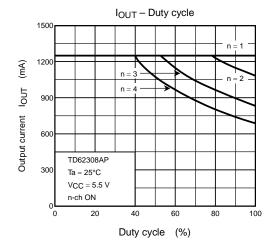
Note 2: C<sub>L</sub> includes probe and jig capacitance

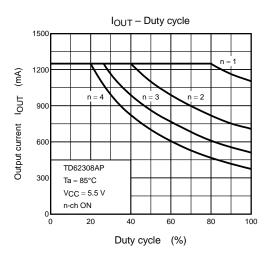


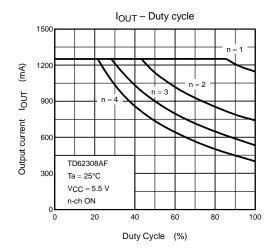


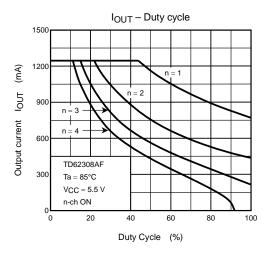








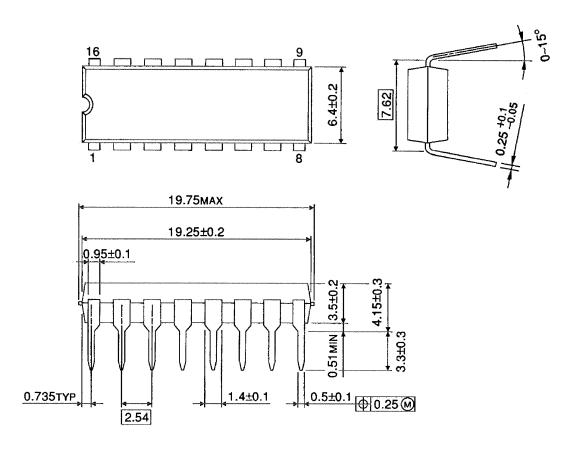




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# **Package Dimensions**

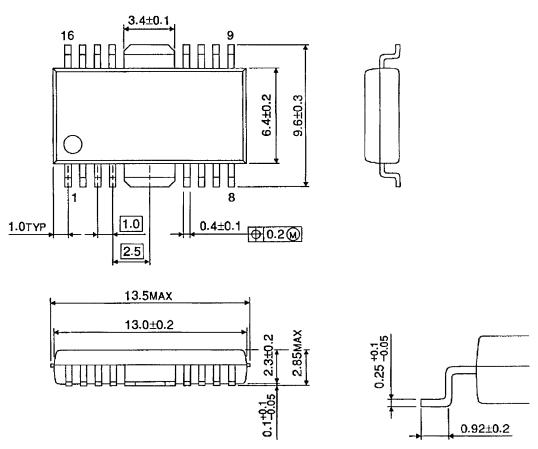


Weight: 1.11 g (typ.)

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# **Package Dimensions**

HSOP16-P-300-1.00 Unit: mm



Weight: 0.50 g (typ.)

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#### **Notes on Contents**

#### 1. Equivalent Circuits

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

#### 2. Test Circuits

Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.

#### IC Usage Considerations

#### Notes on Handling of ICs

- (1) The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.
  Exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.
- (2) Use an appropriate power supply fuse to ensure that a large current does not continuously flow in case of over current and/or IC failure. The IC will fully break down when used under conditions that exceed its absolute maximum ratings, when the wiring is routed improperly or when an abnormal pulse noise occurs from the wiring or load, causing a large current to continuously flow and the breakdown can lead smoke or ignition. To minimize the effects of the flow of a large current in case of breakdown, appropriate settings, such as fuse capacity, fusing time and insertion circuit location, are required.
- (3) If your design includes an inductive load such as a motor coil, incorporate a protection circuit into the design to prevent device malfunction or breakdown caused by the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF. IC breakdown may cause injury, smoke or ignition.

  Use a stable power supply with ICs with built-in protection functions. If the power supply is unstable, the protection function may not operate, causing IC breakdown. IC breakdown may cause injury, smoke or ignition.
- (4) Do not insert devices in the wrong orientation or incorrectly. Make sure that the positive and negative terminals of power supplies are connected properly. Otherwise, the current or power consumption may exceed the absolute maximum rating, and exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion. In addition, do not use any device that is applied the current with inserting in the wrong orientation or incorrectly even just one time.
- (5) Carefully select external components (such as inputs and negative feedback capacitors) and load components (such as speakers), for example, power amp and regulator.

  If there is a large amount of leakage current such as input or negative feedback condenser, the IC output DC voltage will increase. If this output voltage is connected to a speaker with low input withstand voltage, overcurrent or IC failure can cause smoke or ignition. (The over current can cause smoke or ignition from the IC itself.) In particular, please pay attention when using a Bridge Tied Load (BTL) connection type IC that inputs output DC voltage to a speaker directly.

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#### Points to Remember on Handling of ICs

#### (1) Heat Radiation Design

In using an IC with large current flow such as power amp, regulator or driver, please design the device so that heat is appropriately radiated, not to exceed the specified junction temperature (Tj) at any time and condition. These ICs generate heat even during normal use. An inadequate IC heat radiation design can lead to decrease in IC life, deterioration of IC characteristics or IC breakdown. In addition, please design the device taking into considerate the effect of IC heat radiation with peripheral components.

#### (2) Back-EMF

When a motor rotates in the reverse direction, stops or slows down abruptly, a current flow back to the motor's power supply due to the effect of back-EMF. If the current sink capability of the power supply is small, the device's motor power supply and output pins might be exposed to conditions beyond maximum ratings. To avoid this problem, take the effect of back-EMF into consideration in system design.

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